

Appln. No.: 10/663,028  
Amendment Dated April 23, 2007  
Reply to Office Action of December 26, 2006

SDC-103US  
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**Amendments to the Claims:** This listing of claims will replace all prior versions, and listings, of claims in the application

Listing of Claims:

1. (Currently Amended) A method for controlling a directional antenna to receive a radio frequency (RF) signal comprising the steps of:

providing multiple direction signals to the directional antenna to receive the RF signal from multiple corresponding directions;

determining information concerning respective frequency spectra of the RF signal received from each of the multiple directions;

determining information concerning respective signal strengths of the RF signal received from each of the multiple directions;

analyzing the determined information concerning the respective signal strengths and the information concerning the respective frequency spectra of the RF signals to select a preferred direction of the multiple directions from which to receive the RF signal; and

sending a direction control signal to the antenna to receive the RF signal from the preferred direction.

2. (Canceled)

3. (Currently Amended) A method according to claim 12, wherein the information concerning the respective signal strengths of the RF signals is a signal strength metric defined by the following equation:

$$\text{Signal Strength} = 100 \times \left( 1 - \frac{G}{G_{\max}} \right)$$

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where  $G$  represents an amount of amplification provided to the RF signal by an automatic gain control (AGC) amplifier and  $G_{\max}$  represents a maximum amount of amplification provided by the AGC amplifier.

4. (Original) A method according to claim 1, wherein the information concerning respective frequency spectra of the RF signal includes performance metrics for a decision feedback equalizer (DFE) applied to the RF signal received from respective ones of the multiple corresponding directions.

5. (Original) A method according to claim 4, wherein the performance metric is a measure of minimum mean squared error (MMSE) for the DFE.

6. (Original) A method according to claim 5, wherein the performance metric is an approximation of the MMSE of the DFE represented by the equation:

$$\text{MMSE(DFE)} \approx \sigma_s^2 G \exp \left( \frac{\delta}{2\pi} \sum_k \ln \left( \frac{\lambda}{P_k} \right) \right)$$

where  $\sigma_s^2$  is the source signal power,  $G$  is an measure of amplification applied to the signal,  $\lambda = \sigma_n^2 / \sigma_s^2$ , where  $\sigma_n^2$  is the noise power,  $\delta$  is a differential frequency that defines a frequency band and  $P_k$  is a measure of signal power in the  $k^{\text{th}}$  frequency band.

7. (Original) A method according to claim 5, wherein the performance metric is an approximation of the MMSE of the DFE represented by the equation:

$$\text{MMSE(DFE)} = \sigma_s^2 \frac{\sum_k |h_{\min_k}|^2}{\lambda \sum_k |h_k|^2 + 1}$$

where  $\sigma_s^2$  is the source signal power,  $\lambda = \sigma_n^2 / \sigma_s^2$ , where  $\sigma_n^2$  is the noise power,  $h_k$  is the  $k^{\text{th}}$  term in a channel multipath error model,  $h_{\min_k}$  is a  $k^{\text{th}}$  tap coefficient of a decision

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feedback equalizer that minimizes the mean squared error between the equalized signal and a known reference signal.

8. (Original) A method according to claim 1, wherein the information concerning respective frequency spectra of the RF signal includes performance metrics for a linear equalizer (LE) applied to the RF signal received from respective ones of the multiple corresponding directions.

9. (Original) A method according to claim 8, wherein the performance metric is a measure of minimum mean squared error (MMSE) for the LE.

10. (Currently Amended) A method according to claim 9, wherein the performance metric is an approximation of the MMSE of the LE represented by the equation:

$$\text{MMSE(LE)} \approx \frac{\sigma_n^2 G \delta}{2\pi} \sum_k \frac{1}{P_k}$$

where  $\sigma_n^2$  is the noise power,  $\sigma_s^2$  is the source signal power, G is a measure of amplification applied to the signal,  $\delta$  is a differential frequency that defines a frequency band and  $P_k$  is a measure of signal power in the  $k^{\text{th}}$  frequency band.

11. (Currently Amended) A method according to claim 9, wherein the performance metric is an approximation of the MMSE of the LE represented by the equations:

$$\text{MMSE(LE)} \approx \frac{\sigma_n^2 G \delta}{2\pi} \sum_k (\bar{P} - \tilde{P}_k),$$

$$\bar{P} = \frac{1}{N} \sum_k P_k, \quad \tilde{P}_k = P_k - \bar{P}$$

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where  $\sigma_n^2$  is the noise power,  $\sigma_s^2$  is the source signal power,  $G$  is a measure of amplification applied to the signal,  $\delta$  is a differential frequency that defines a frequency band,  $N$  is a number of frequency bands and  $P_k$  is a measure of signal power in the  $k^{\text{th}}$  frequency band.

12. (Original) A method according to claim 1, wherein the information concerning respective frequency spectra of the RF signal includes a respective spectral flatness metric for the RF signal received from each of the multiple corresponding directions.

13. (Original) A method according to claim 12, wherein the spectral flatness metric,  $SP$ , is represented by the equation:

$$SP = \log \left( \frac{1}{2\pi} \int_{-\pi}^{+\pi} Q'(f) df \right) - \frac{1}{2\pi} \int_{-\pi}^{+\pi} \log Q'(f) df$$

where  $Q'(f) = |h_{\min}(f)|^2 Q(f)$ ,  $h_{\min}(f)$  is the response of the equalization filter at frequency  $f$  and  $Q(f)$  is the power spectrum of the RF signal.

14. (Original) A method according to claim 1, wherein the information concerning the respective frequency spectra of the RF signal includes an interference degradation metric for the RF signal received from each of the multiple corresponding directions.

15. (Original) A method according to claim 14, wherein the interference degradation metric is represented by the equation

$$MSE(D_f) \approx 10^{(\Delta_f - D_f)/10}$$

where  $MSE$  is the mean squared error,  $D_f$  is an estimate of the interference at a frequency  $f$ ,  $\Delta_f = 10 \log_{10}(MSE(D_f)) + D_f$  is a typical interference suppression value and  $D_f$  is a desired to undesired ratio interference value.

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16. (Original) A method for controlling a directional antenna to receive a radio frequency (RF) signal comprising the steps of:

providing multiple direction signals to the directional antenna to receive the RF signals from multiple corresponding directions;

measuring at least a first characteristic of the RF signal received from each of the multiple directions;

selecting one of the multiple directions responsive to the measured first characteristic to define a selected direction;

providing further direction signals to the directional antenna to receive the RF signal from respective further directions related to the selected direction;

measuring at least a second characteristic, different from the first characteristic, of the RF signal received from each of the further directions to select a preferred direction from which to receive the RF signal; and

sending a direction control signal to the antenna to receive the RF signal from the preferred direction.

17. (Original) A method according to claim 16, wherein the first and second characteristics of the RF signal are respectively different channel quality metrics.

18. (Original) A method according to claim 16, wherein the first characteristic of the RF signal is selected from a group consisting of a power level of the RF signal, a minimum mean squared error (MMSE) of a decision feedback equalizer (DFE), a MMSE of a linear equalizer (LE), a spectral flatness metric and an interference degradation metric and the second characteristic of the RF signal is selected from a group consisting of a minimum mean squared error (MMSE) of a decision feedback equalizer (DFE), a MMSE of a linear equalizer (LE), a spectral flatness metric and an interference degradation metric.

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19. (Original) A method according to claim 16, wherein the multiple direction signals include signals that cause the directional antenna to receive RF signals from at least two different directions and the further direction signals cause the directional antenna to receive RF signals from a plurality of direction angles proximate to the selected direction.

20. (Original) A method according to claim 19, wherein the multiple direction signals include four cardinal directions, North, East, South and West, and the further direction signals include at least direction angles between the selected direction and each of the adjacent directions.

21. (Currently Amended) Apparatus comprising:

a directional antenna, responsive to a direction control signal for receiving a radio frequency (RF) signal preferentially from a direction indicated by the direction control signal;

a controller which provides multiple direction control signals to the directional antenna to receive the RF signal from multiple corresponding directions;

a power spectrum measurement processor which determines information concerning respective frequency spectra of the RF signal received from each of the multiple directions;

an automatic gain control circuit which provides respective measures of signal strength for the RF signal received from each of the multiple corresponding directions;

a processor which analyzes the determined information and the measures of signal strength to select a preferred direction of the multiple corresponding directions from which to receive the RF signal;

whereby the preferred direction control signal is sent to the directional antenna to receive the RF signal from the preferred direction.

22. (Canceled)

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23. (Currently Amended) Apparatus according to claim ~~21~~22, further comprising an equalization filter which provides, to the processor, a respective measure of equalization error for the RF signals received from each of the multiple corresponding directions.

24. (Original) Apparatus according to claim 23, wherein the equalization filter is a decision feedback equalizer.

25. (Original) Apparatus according to claim 23, wherein the equalization filter is a linear equalizer.